

ENGINE GENERATOR APPARATUS

BACKGROUND OF THE INVENTION

Field of the Invention

The present invention relates to an engine generator apparatus and particularly to an engine generator apparatus such as a generator facility for private use or a small-sized cogeneration system having a function for interconnecting with an electric power system.

Description of the Related Art

Generator apparatuses for private use have widely been provided for emergency use in case of blackout or power failure. Recently, private use cogeneration type generator apparatuses which can be interconnected with electric power systems for improvement of the efficiency of operation are getting popular. Such a cogeneration type private use generator apparatus comprises a small generator driven by a gasoline engine or a gas engine fueled with gas fuel such as town gas.

For smooth interconnection or parallel operation of two electric power system, the cogeneration type generator apparatus needs to comply with the guideline for technical requirements for interconnection (issued by the Ministry of Trade) which stipulates technical standards including a range of outputs of power systems and protections for the power system in case of ground fault or short-circuit. It

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is hence necessary to constantly monitor the apparatus for inhibiting discrepant actions from the requirements of the guideline due to a fault in the operation of the generator.

The output of the generator described above is rectified with three phase windings and converted into an alternating current with a commercial frequency (the source frequency of a power system). A fault in the operation of the ordinary or relatively large output generator may be detected by constantly monitoring the output voltage of each of the three phase windings. However, when a small output generator apparatus such as a private use cogeneration system which is substantially low in the price is quipped with the same monitoring means as of the large output power generator, its overall price will increase thus resulting in the higher production cost.

SUMMARY OF THE INVENTION

The present invention is developed in view of the above drawback and its object is to provide an engine generator apparatus which can detect a fault in the operation of its generator section with a simple arrangement.

A first feature of this invention is that an engine generator apparatus for rectifying and converting an alternating output of a generator, which has multi-phase windings and is driven by an engine, and converting the rectified output by an inverter into an alternating current at the frequency of a power system and the alternating current

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is interconnected with the source of said power system, comprising, a means for starting the interconnection with the system source when a direct current voltage rectified rises up to first predetermined level after the start up of the engine and then increasing the output of the inverter, 5 means for canceling the interconnection when the direct current voltage drops down to below second predetermined level, and for re-starting the interconnection with the system source when the direct current voltage returns back 10 to the first predetermined level, and a fault detecting means for judging that the power generator has a fault when the direct current voltage drops down to below the second predetermined level after the re-starting of the interconnection.

15 According to the first feature of the present invention, when the direct current voltage rectified after the start up of the engine rises up to the predetermined level, the connection with the electric power system is made and the output of the inverter is increased. At the time, the direct 20 current voltage drops down if a fault such as line breakage in the windings occurs. However, the direct current voltage rises up again upon cancellation of the interconnection. It can then be judged that the generator has a fault when the direct current voltage drops down after the parallel 25 operation of the two power system is established once again.

A second feature of the present invention is that the

output of the inverter is gradually increased at the start
of the interconnection with the power system source. When
the engine is interconnected with a large load such as a
rated load after warming up, it may cause hunting or slowdown
5 (stalling) of the revolution. According to the second
feature, while the engine runs steadily, its adverse effects
on the system source at the interconnection can be minimized.
As a result, the direct current voltage which is susceptible
to the exertion of large loads on the engine can be maintained
10 stable and its change which results in misjudgment for the
fault detection can be eliminated.

A third feature of the present invention is comprising
a means where a generator fault signal is outputted, when
the canceling and the re-start of the interconnection with
15 the power system is repeated, the fault detecting means
examines whether or not the generator has a fault. According
to the third feature, the generator fault signal is outputted
when frequent canceling and re-start interconnection with
the power system occurred. This prudent judgment improves
20 the accuracy of the fault detection.

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a block diagram of an engine generator apparatus
illustrating one embodiment of the present invention;

25 Fig. 2 is a flowchart showing the operation of an ECU
at the start up;

Fig. 3 is a flowchart showing the operation of an inverter

controller at the start up;

Fig. 4 is a flowchart showing the operation of the ECU when a fault occurs;

5 Fig. 5 is a flowchart showing the operation of the inverter controller when a fault occurs;

Fig. 6 is a block diagram of a cogeneration system illustrating another embodiment of the present invention; and

10 Fig. 7 is a block diagram of a primary part of an conventional engine generator apparatus.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

One embodiment of the present invention will be described in more detail referring to the relevant drawings.

Fig. 1 is a block diagram of the engine generator apparatus.

15 As shown, an engine operated generator 10 comprises an engine 11 and a generator 12. The generator 12 is driven by the engine 11 for generating an alternating current output responding to the number of revolutions. The generator 12 comprises a rotor joined to the engine 11 and a stator on which three phase windings are wound. The output terminal
20 of the three phase windings is connected with an inverter unit 13. The inverter unit 13 converts the alternating current output of the generator 12 into an alternating current of the quality equivalent (in voltage, frequency, noise, and other factors) to that of the commercial power supply, then the output is connected to the commercial power

system as timed in phase with the same of the system.

More specifically, the inverter unit 13 comprises a converter 131 for converting the alternating current output of the generator 12 into a direct current, an inverter circuit 133 for converting the direct current received from the converter 131 into an alternating current with the frequency and the voltage of the commercial power system, a filter circuit 134, and a connector relay 135. The alternating current output of the inverter unit 13 is connected by the connector relay 135 and a main switch 136 to the commercial power system 14 and also to a domestic electrical load 15 (for example, in a private use power system).

Also, the inverter unit 13 includes an inverter controller 137 for switch controlling the FET of the inverter circuit 133. The inverter controller 137 are arranged responsive to an output current I_o , an output voltage V_{dc} of the converter circuit 131, and a signal from a system protector 138 for controlling the switching action of the connector relay 135 as providing a function for protecting the inverter circuit 133.

The system protector 138 monitors the voltage and frequency of the output of the generator 12 and if the voltage or the frequency is different from the reference level or the failure of the power supply is occurred, generates and supplies an error signal to the inverter controller 137 which in turn open the connector relay 135 thus release the parallel

operation to protect the system. Failure in the power supply may be judged from jumping in the phase of the system. Alternatively, while the inverter output is periodically shifted in the phase, the failure may be judged from a degree of phase shift. The inverter controller 137 includes a nonvolatile memory such as an EEPROM for storage of data of the failure and data of the (unusual) stop motion when the failure takes place in the inverter unit 13 or the commercial power system 14.

The connector relay 135 is closed to connect the inverter unit 13 for parallel operation and is opened to disconnect the inverter unit 13 for parallel off. In addition, the connector relay 135 serves as a disconnector for protection of the system and is opened instantly when the system has a fault. The switching action of the connector relay 135 is controlled by the inverter controller 137 and the system protector 138, either may be implemented by a microcomputer. The connector relay 135 remains opened (parallel operation is released) when the main switch 136 is disconnected.

An ECU 38 is provided for controlling the engine 11. When the connector relay 135 is kept opened at a predetermined length of time, the ECU 38 generates a stop signal to stop the engine 11. The ECU 38 hence includes a nonvolatile memory such as an EEPROM for storage of data of the fault or data of the stop motion by the fault as well as a display such as an LED for displaying the fault.

A communications unit 139 is provided between the ECU
38 and a combination (which may be referred to as an inverter
side opposite to the ECU side) of the inverter controller
137 and the system protector 138 for communication of each
5 state of both sides. A power source 140 is connected to
the output terminal of the inverter unit 13 for supplying
power to a drive source and a control source for both the
engine generator 10 and the inverter unit 13.

The engine 11 is supplied with a mixture of air and
10 gas fuel produced by a mixer 33. A proportional valve 35
is provided across a gas intake tube 34 and its opening can
determine the air-fuel ratio. The mixture of air and gas
fuel is combusted in the engine 11 and exhausted from an
exhaust tube 36. An oxygen sensor 37 is provided across
15 the exhaust tube 36. In response to the density of oxygen
detected by the oxygen sensor 37, the ECU 38 drives the
proportional valve 35 to set the air-fuel ratio to
theoretical air-fuel ratio for complete combustion.
Before the oxygen sensor 37 is activated, the engine 11 is
20 driven in a lean-burning mode in order to minimize the
discharge of toxic substances in accordance with the exhaust
regulations.

Figs. 2 and 3 are flowcharts showing the actions of
the engine generator (or ECU) control side and the inverter
25 control side of the system at the start up of the engine
generator 10. The control action starts when the main switch

136 is turned on but the motion of the engine 11 is stopped by the occurrence of a fault.

The procedure of steps in the ECU 38 control side will now be explained referring to Fig. 2. At Step S1, it is judged from data stored in the nonvolatile memory whether or not the engine 11 is stopped by a fault on the engine 11. When the engine is stopped by a fault, the fault is displayed on the LED for notifying the user at Step S4. The data in the memory then remains unchanged. When the stop motion is not caused by the fault on the engine 11, the procedure advances to Step S2 for examining whether or not the stop motion is caused by a fault on the inverter unit 13. This examination is based on the data stored in the nonvolatile memory.

When the inverter unit 13 has a fault, the procedure jumps to Step S4. When the inverter unit 13 has no fault, the procedure goes to Step S3.

As it has been judged that the engine 11 is stopped by the fault on either the engine 11 or the inverter unit 13, the procedure goes to Step S4 for displaying the fault. This is followed by Step S5 where it is examined whether or not the engine stop is released by users handling. When the stop motion is canceled by the user ("yes" at Step S5), the procedure moves to Step S3. A switch (not shown) for canceling the stop motion by the fault may be provided independently of the main switch 136 in order to clear

communication of the users mind for canceling the stop motion.

It is then examined at Step S3 whether a heat request is received or not from a controller (Fig. 5) for detecting the size of thermal load, i.e. the command for starting up the engine 11 is received or not. The thermal load in the form of a hot-water tank and the controller will be explained later in more detail.

When the heat request is received, the procedure goes to Step S6 where it is examined whether or not the engine 11 has a fault. If not, the procedure advances to Step S7 where the communication unit 139 is activated for inquiring of the inverter controller 137 about the state of the inverter unit 13. It is examined from a response from the inverter controller 137 at Step S8 whether the inverter unit 13 has a fault or not. If the inverter unit has not fault, the procedure goes to Step S9 for starting the engine 11. When the engine 11 is started up, its start is communicated to the inverter controller 137 through the communication unit 139.

It is then examined at Step S10 whether the oxygen sensor 37 is activated or not. When the sensor 37 is activated, a signal of "inverter start permission" is transmitted to the inverter controller 137 through the unit 139, and the inverter is started and apply the load (S11). The activation of the oxygen sensor 37 may be judged when a predetermined

length of time has elapsed after the start up of the engine
11 or when the ambient temperature of the oxygen sensor 37
has increased to a predetermined level.

The process in the inverter controller 137 will now
5 be explained referring to Fig. 3. As the main switch 136
has been turned on, it is examined from the data in the
nonvolatile memory at Step S12 whether a power failure is
detected or not. When the power failure is detected, the
procedure goes to Step S13 for hesitation or time lag. After
10 the hesitation of a predetermined length of time (e.g. 150
seconds), the procedure goes to Step S14. If no power
failure is detected, the procedure jumps to Step S14 from
Step S12.

The time lag at Step S13 has the following advantage.
15 After a power failure occurs, its location may be identified
through temporally re-energizing that is operated by the
power company. Once a power failure occurs, it may be
repeated after the re-energization. If so, when a power
failure occurs with the main switch 136 being connected,
20 the following re-energization starts up the generator
apparatus. This may make the investigation for finding the
cause of the power failure difficult. However, the
hesitation or time lag of 150 seconds provides ease of the
investigation.

25 It is then examined at Step S14 whether the power system
has a fault or not. If the power system has not fault, the

procedure goes to Step S15 where it is examined whether the inverter unit 13 now has a fault or not. If there is not a fault, the procedure moves to Step S17 for starting the checkup of the generator 12. When the inverter unit 13 has 5 a fault, the procedure goes to Step S18 for storing a memory with a data of "inverter fault" and returns back to Step S14.

When it is judged at Step S14 that the power system has a fault, the judgment at Step S14 is maintained until 10 the fault on the power system is eliminated. The data in the nonvolatile memory indicative of the fault of the inverter unit 13 is cleared when the user cancels the usual state and the judgment at Step S5 is affirmative. As a result, 15 the inverter fault is eliminated. This information about the inverter unit 13 is transferred to the ECU 38 side as a response to the requiring at Step S7.

It is then examined at Step S19 whether the direct current voltage Vdc after the rectification process exceeds a predetermined level (e.g. 380 V) or not. When the voltage 20 exceeds the predetermined level, the procedure advances to Step S20 where the connector relay 135 is closed by the signal of "inverter start permission" transmitted at Step S1 for starting the parallel operation with the commercial power system.

25 This is followed by Step S21 where the output of the inverter unit 13 is increased. It is examined at Step S22

whether or not the direct current voltage Vdc is kept exceeding the predetermined level (e.g. 380 V). If the Step S22 is affirmative, the procedure advances to Step S23 where it is examined whether the output reaches a rated level (e.g. 5 1 kW) or not. If the output is not reached the rated level, the procedure returns back to Step S21 for increasing the output of the inverter unit 13. When the output reaches its rated level, it is judged that the operation is normal and the procedure for examining the inverter fault at the start up is terminated. Because of Steps S21 to S23, the soft startup with gradually increasing the output can be performed.

On the other hand, when the direct current voltage Vdc is smaller than the predetermined level after increasing the output of the inverter unit 13 with the output which is lower than the rated level ("negative" at Step S23), the procedure moves from Step S22 to Step S24. It is examined at Step S24 whether or not the judgment that the direct current voltage Vdc is not higher than the predetermined level is repeated at a predetermined number of times (e.g. 10 15 five times). If Step S24 is affirmative, it is judged that the generator 12 has a fault and the parallel operation with the commercial power system is canceled thus stopping the inverter controlling process. If it is judged "not" at Step 20 25 S24, the procedure goes to Step S25 for canceling the parallel operation. After providing a time lag at Step S26 for the

predetermined length of time (150 seconds), the procedure goes back to Step S20 for re-starting of the parallel operation. The procedure may be shifted from Step S26 to Step S19 instead of S20.

5 When it is judged negative at Step S19, the procedure goes to Step S27 where it is examined whether or not the direct current voltage Vdc is below the predetermined level throughout a predetermined length of time (e.g. three minutes). When the generator 12 has a fault, it is judged affirmative at Step S27 or affirmative at Step S24, and the procedure goes to Step S24a. At Step S24a, store the nonvolatile memory with the fault of the generator 12 and then the inverter control procedure is terminated.

10 The procedure without the heat request or with the occurrence of a fault after the start up will be explained. Fig. 4 is a flowchart showing the process of the ECU 38. It is examined at Step S30 whether the heat request is received or not. If the request is not received, the procedure goes to Step S31 for stopping the engine 11. After 15 stopping the engine 11, the procedure moves to Step S3 (Fig. 2) for waiting until the heat request is received. When the engine 11 is stopped with no heat request, its information 20 is transferred to the inverter controller 13.

25 When the heat request is received, the procedure advances to Step S32 where it is examined whether the engine 11 has a fault or not. When the engine 11 has a fault, the

procedure goes to Step S33 for stopping the engine 11. As
the engine 11 stops, the nonvolatile memory is stored with
the data of "engine fault" at Step S34 and then, the procedure
moves back to Step S1. If the engine 11 is stopped by the
5 fault on the engine 11, engine stop is transmitted to the
inverter controller 13.

When the engine 11 has no fault, the procedure goes
to Step S35. It is examined at Step S35 whether a fault
signal indicative of a fault in the inverter unit 13 is
10 received or not from the inverter controller 137. When the
fault signal is received from of the inverter unit 13, the
procedure moves to Step S36 for stopping the engine 11. Then,
the nonvolatile memory is stored with a data of "inverter
fault" at Step S37 and the procedure goes back to Step S1.
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If the fault signal is not received from the inverter
unit 13, the procedure goes to Step S38 where it is examined
whether a signal indicative of power system fault is received
or not from the inverter controller 137. When the power
system fault signal is not received, the procedure moves
20 to Step S30. When the signal indicative of power system
fault is received, the procedure moves to Step S39 for
stopping the engine 11 and the procedure returns to Step
S3.

The process of the inverter controller 13 will now be
25 explained referring to Fig. 5. It is examined at Step S40
whether the heat request off is received or not from the

ECU 38. When the heat request off is received, the connection to the power system is released at Step S41 and the procedure moves back to Step S12 (Fig. 3). When the heat request off is not received, the procedure advances 5 to Step S42 where it is examined whether the signal of the engine stop is received or not. When signal of the engine stop is received, the parallel operation is released at Step S43 and the procedure returns to Step S12. If the signal of the engine stop is not received, it is examined at Step 10 S44 whether or not the inverter unit 13 has a fault. When the unit 13 has a fault, the procedure goes to Step S45 for releasing the connection to the commercial power system and the procedure moves back to Step S12.

If the inverter unit 13 has no fault, it is then examined 15 at Step S46 whether the power system has a fault or not. When the power system has not a fault, the procedure goes to Step S47 where it is examined whether the connection or parallel operation is established or not. When the parallel operation is established, the procedure returns back to Step 20 S40.

When it is judged at Step S46 that the power system has a fault, the procedure goes to Step S51 for releasing the parallel operation of the systems. It is then examined 25 at Step S52 whether a power failure occurs or not. When the power failure is detected, the nonvolatile memory is stored with the data indicative of the detection of the

failure at Step S53. If no power failure is detected, the procedure skips Step S53 and jumps to the Step S54. It is then examined at Step S54 whether the power system fault continues throughout a predetermined length of time (e.g. 5 five minutes) or not. If Step S54 is negative, the procedure goes to Step S47. When the parallel operation is not established, the procedure advances to Step S48 where it is examined whether the power system has a fault or not. When the power system has a fault, the procedure moves back to Step S40. If not, the procedure goes to Step S49 for providing a time lag of a predetermined length of time (e.g. 10 150 seconds) and then to Step S50. At Step S50, the parallel operation is started. When the fault continues over the predetermined length of time, the procedure goes to Step 15 S55 where the command of stopping the engine 11 is transmitted to the ECU 38. It is then examined at Step S56 whether the power system has a fault or not. When the fault has been eliminated, the procedure goes to Step S57 for providing a time lag of a predetermined length of time (e.g. 150 20 seconds) and then returned to Step S12 (Fig. 3).

A cogeneration system according to the present invention will be described which include an apparatus for utilizing heat of the exhaust gas from the engine generator. Fig. 6 is a block diagram of the cogeneration system where like components are denoted by like numerals as those shown 25 in Fig. 1. As the engine 11 drives the generator 12, it

generates heat which is recovered with a heat recovery unit 16 of the engine 11 through heat exchange. The recovery of heat may preferably be carried out on all the high-temperature regions of the engine 11 including a
5 muffler tube. As the cooling water is carried through a tube 18 which extends across the heat recovery unit 16, it serves as a medium for conveying the heat to a hot-water storage tank 17.

The hot water storage tank 17 contains a output heat
10 exchanger (referred to as a first heat exchanger hereinafter) 20 communicated with the conduit 18. The water supplied from a water source 31 to the hot water storage tank 17 is then heated by the first heat exchanger 20 to turn to a hot water. The hot water heated and saved in the
15 hot water storage tank 17 is fed for further use to a hot water supply unit 21, which is a first thermal load.

A second heat exchanger 22 is provided above the first heat exchanger 20 in the tank 17. The second heat exchanger 22 is communicated to a conduit 23, which in turn connected with a heating system 24, such as a central heating system or a floor heating system, acting as a second thermal load.
20 The second conduit 23 forms a second hot water path, which is separated from the hot water path for supplying the hot water from the hot water storage tank 17 to the hot water supply unit 21. The second hot water path 23 performs
25 secondary exchange of the heat from the hot water storage

tank 17 thus increasing the efficiency of the heat recovery.

In the second hot water path 23, there are also provided
5 a re-heating boiler 25 and a three-directional valve 26. The re-heating boiler 25 is provided with a pump 27 for circulating the hot water throughout the second hot water path 23. The three-directional valve 26 is a means for switching the flow of the hot water to a bypass 28 or to the heating system 24. The following passages are selected by operating the three-directional valve 26. When the
10 three-directional valve 26 is switched to the heating system 24, the passage is opened for conveying the hot water via the re-heating boiler 25 and the heating system 24 from and to the hot water storage tank 17. When the three-directional valve 26 is switched to the bypass 28, the passage is opened
15 for conveying the hot water via the bypass 28, not the heating system 24, from and to the hot water storage tank 17.

A temperature sensor TS1 is provided in the hot water storage tank 17 and information about the temperature TI of the hot water measured by the temperature sensor TS1 is
20 transmitted to a controller 29. The temperature sensor TS1 may be located at an appropriate height level between substantially the uppermost of the first heat exchanger 20 and the lowermost of the second heat exchanger 22 and most preferably at a midway between the first heat exchanger 20 and the second heat exchanger 22. It is very likely that,
25 due to the effect of convection, the temperature of the hot

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water is lower at substantially the lowermost of the hot water storage tank 17 and higher at substantially the uppermost. As the temperature sensor TS1 is located at the midway, it can detect an average value of the temperature in the hot water storage tank 17.

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In response to the temperature information TI, the controller 29 controls the start and stop operation of the engine 11. Since the temperature information TI represents the demand of heat from the hot water supply unit 21 which draws the hot water directly from the hot water storage tank 17 or from the heating system 24 which draws the hot water indirectly via the second heat exchanger 22, the controller 29 judges that the demand exceeds when the temperature information TI is not higher than a reference level Tref-1 and drives the engine 11 to generate the heat. On the other hand, when the temperature information TI is higher than the reference level Tref-1, the controller 29 judges that a sufficient level of the heat energy is saved in the hot water storage tank 17 and turns the heat request off then stops the engine 11.

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The reference level Tref-1 of the temperature is determined from multiple parameters of the type and the magnitude of the thermal load (i.e. the type and the capacity of the hot water supply unit 21 and the heating system 24), the thermal output of the engine operated generator 10, the volume of the hot water storage tank 17, and so on. The

reference level T_{ref-1} has a hysteresis for ensuring a stable operation of the engine 11, i.e. avoiding frequent start and stop operations.

In case that the engine 11 is controlled with the temperature information TI , its operation may be contemplated for driving the generator 12 to generate a constant power output or, in an electrical load dependent mode, to generate a variable output depending on the magnitude of the electrical load 15. In the constant power output mode, the engine 11 as a driving power source is operated to make the number of its revolutions constant and thus its operation will ensure a higher level of the efficiency minimizing the consumption of fuel and releasing an acceptable level of the exhaust gas. If the demand of electricity exceeds the output of the generator 12, a deficiency in the electricity is covered by the supply from the commercial power system 14.

The temperature of the hot water in the hot water storage tank 17 is significantly varied depending on the consumption of the hot water, i.e. the demand of thermal energy, and the mode of the operation of the engine operated generator 10, e.g. either the constant output mode or the electrical load dependent mode. For example, in a system where when the consumption of the hot water is low, the temperature of the hot water can be maintained to about 80°C with the generator 12 operating in response to the temperature

detected by the temperature sensor TS1, either abrupt, bulky
consumption of the hot water resulting from the demand of
heat given simultaneously from both the hot water supply
unit 21 and the heating system 24 or the startup of the system
5 may cause the temperature of the hot water in the hot water
storage tank 17 to drop down to as a low degree as of the
cool water supplied.

In case that the reference temperature of the hot water
in the hot water storage tank 17 is hardly maintained with
the heat collected from the engine 11, the re-heating boiler
25 functions effectively. The hot water controller 30
provides the re-heating boiler 25 and the three-directional
valve 26 with a command "B" for re-heating and a command
"C" for switching, respectively. The hot water controller
30 is preset with a lower reference temperature Tref-L which
is lower than the reference temperature Tref-1 and when the
temperature T1 of the hot water in the hot water storage
tank 17 drops down to lower than the lower reference
temperature Tref-L, it turns on the re-heating command "B"
15 and the switching command "C". As the re-heating command
"B" is turned on, the re-heating boiler 25 starts operating.
As the switching command "C" is turned on, the
three-directional valve 26 shifts its passage to the bypass
20. Accordingly, the hot water heated by the re-heating
boiler 25 circulates through the conduit 23 and increases
25 the temperature of the hot water in the hot water storage

tank 17 via the second heat exchanger 22.

A second temperature sensor TS2 is provided above the temperature sensor TS1. When the temperature T1 is below the reference temperature Tref-1 or the temperature T2 outputted by the temperature sensor TS2 is not higher than a reference temperature Tref-2 ($>Tref-1$), the controller 29 may generate and transfer the heat request to the ECU 38.

When the temperature T1 outputted by the temperature sensor TS1 exceeds a reference temperature Tref-3 (e.g. 70 °C) which is higher than the reference temperature Tref-1, the operation of the engine operated generator 10 is stopped. It is judged that the energy of heat stored in the hot-water storage tank 17 is sufficient as expressed by the temperature T1 outputted by the temperature sensor TS1 which reaches the reference temperature Tref-3.

A procedure of controlling the start/stop operation of the engine operated generator 10 based on the scale of a thermal load represented by the temperature of water in the hot water storage tank 17 is depicted in the specification of Japanese Patent Application (Heisei) 11-106296 that is filed by this applicant.

Fig. 7 is a block diagram illustrating an arrangement of primary functions according to the present invention. As shown, a direct current voltage detector 39 measures the direct current voltage Vdc rectified by a converter 131.

A first fault monitor 40 is arranged responsive to a command of generator fault detection for starting the monitoring of the direct current voltage Vdc. When the direct current voltage Vdc exceeds a threshold level Vdcth (e.g. 380 V) 5 within a predetermined length of time (e.g. three minutes), a signal for starting the parallel operation is outputted from the first fault monitor 40. Alternatively, when the direct current voltage Vdc dose not exceed the threshold level Vdcth within the predetermined length of time, a signal 10 for generator fault is outputted.

Upon receiving the parallel operation start signal, a relay 135 is closed and an output increasing unit 41 is switched on to gradually increase the output of an inverter unit 133 in the inverter unit 13. When receiving the 15 parallel operation start signal, an inverter output detector 42 starts measuring the output of the inverter unit 13.

Upon receiving the parallel operation start signal, a second fault monitor 43 monitors the outputs of the direct current voltage detector 40 and the inverter output detector 42. When the inverter output exceeds a rated level (e.g. 20 1 kW) with the direct current voltage Vdc remaining higher than the threshold level Vdcth, a generator normality signal is outputted from the second fault monitor 43.

In case that the direct current voltage Vdc is declined 25 to below the threshold level Vdcth before the inverter output reaches its rated level after the parallel operation

start signal is outputted, the relay 135 is opened up thus allowing the fault signal to be released throughout a predetermined length of time T. The time length T is provided for returning the direct current voltage Vdc to its threshold level Vdcth by releasing the parallel operation and thus having no load. For example, this time length is a duration through which the direct current voltage Vdc is returned back to its threshold level after the first of three phase windings is disconnected. As the fault signal is inverted and received by a gate 44, the relay 135 is opened. Simultaneously, the fault signal is received by a counter 45 which increments the counter value at every rise of the fault signal.

When the fault signal is decayed after the predetermined length of time T, the relay 135 is closed again, thus allowing the second fault monitor 43 to repeat the above action based on the outputs of the direct current detector 40 and the inverter output detector 42. As the counter 45 counts up to its setting number, it generates a count-up signal as the generator fault signal. When the inverter output reaches its rated level with the direct current voltage Vdc remaining higher than its threshold level Vdcth before the count up of the counter 45, the generator normality signal is outputted.

The role of the counter 45 is to increase the accuracy in the detection of faults. Alternatively, once the direct

current voltage drops below the threshold level after the load is connected, it is then judged that the a fault occurs with no use of the counter 45. The detection signal of the fault on the generator 12 is transferred to the ECU 38 which
5 then stops the engine 11.

As set forth above, with the features of the present invention defined in claims 1 to 4, the direct current voltage just after the rectification drops down upon establishment of the parallel operation with commercial power system if the generator has a fault such as line breakage in the windings. The drop in the direct current voltage is eliminated by releasing the parallel operation. When the parallel operation is turned off and then turned on again, it can be judged that any drop in the direct current voltage derives from a fault on the generator. This allows the fault detection to be simply carried out without monitoring the output of each of three phase windings of the generator.
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According to the second claim of the present invention, the introduction of a large load with rapid increase after warming up action can be eliminated thus minimizing adverse effects on the power system upon the connection. As a result, the direct current voltage after the rectification which is susceptible to the exertion of such large loads can be maintained stable and its change which results in
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25 misjudgment for the fault detection can be eliminated.

According to the third feature of the present invention,

the fault can repeatedly be examined thus improving the accuracy of the fault detection.